

APPLICATION NOTE



SCA11H HTTP API SAMPLE CODE



General Description

This document describes a simple method for interfacing with the SCA11H BCG sensor node through HTTP API. The method is described with a Python example code, which is included at the end of this document.

The example code can be used to read BCG info (\bcg) and calibration information (\bcg\cali), and it can as well be used to trigger empty and occupied bed calibrations.

The HTTP API itself is described in detail in HTTP API specification and it can be found on the Murata SCA11H product website. SSDP Discovery, for which a sample code is provided on the aforementioned website, can be used to find the node ip.

Output of the HTTP API sample code

The example code includes both BCG and calibration info HTTP GET functions. These can be substituted with different HTTP API requests in accordance to the HTTP API specification.

An example of a response to a HTTP GET to /bcg (BCG info): {"version":"BCG Sensor_3.0.0.0","mode":1,"pars":"7000,270,5000,0,1500,7","dir":1}

version: BCG module version,

mode: BCG data (0), raw data (1), calibration phase 1 (2) and phase 2 (3). pars: calibration parameters: var_level1 (Signal High), var_level2 (Signal Low), stroke_vol (Min Amplitude), tentative_stroke_vol, signal_range (Typ Amplitude), to_micro_g (Scale) dir: measurement direction, 1 is normal, 0 is inverted

Examples of a response to a HTTP GET to /bcg/cali (calibration info): {"status":-2} (no calibration done)

{"status":0,"phase":1,"step":255} (only empty bed calibration done)

status: calibration status info phase: calibration phase step: calibration step

The example code can also be used to trigger the desired embedded calibration process using /bcg/cali POST (message of type {"phase": 2}). As a response, an error number is returned.

Example return: {"errno":0} (no errors, calibration successful)



sendMessage(...)

Sends a HTTP GET or PUSH command to the selected ip (node), depending on the inputs.

calibrationMenu(...)

A menu for choosing the desired function out of the following options:

1: Calibration info;

- returns the calibration parameters fetched from the node.
- 2: Empty bed calibration
 - triggers phase 1 (empty bed) calibration in the node
 - prints, whether calibration is successful or not
- 3: Occupied bed calibration
 - triggers phase 2 (occupied bed) calibration in the node
 - prints, whether calibration is successful or not

main(...)

Main function with an initial menu, where either (1) BCG info or (2) calibration menu can be requested. Prints out BCG info fetched from the BCG node if 1 is entered, runs calibrationMenu(...) if 2 is entered.



4 (5)

Example Python code

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ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT # LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS # FOR A PARTICULAR PURPOSE ARE DISCLAIMED. IN NO EVENT SHALL THE MURATA BE LIABLE FOR ANY DIRECT, INDIRECT, # HORATA BE LIABLE FOR ANI DIRECT, INDIRECT, # INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES # (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR # SERVICES; LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) # HOWEVER CAUSED AND ON ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, IN ANY WAY OUT OF THE USE OF THIS SOFTWARE, EVEN IF ADVISED OF THE # POSSIBILITY OF SUCH DAMAGE. # Python 3.x import urllib.request import urllib.error import base64 # Windows only! import msvcrt import time username = 'admin' # Username to access HTTP API password = 'admin' # Password to access HTTP API ip = input('Insert IP address: ') # IP of the BSN ip = 'http://' + ip# HTTP Basic authentication headers = { 'Authorization': 'Basic ' + base64.b64encode((username + ':' + password).encode('utf-8')).decode() } def sendMessage(path,body): # Sends HTTP GET/POST to predefined IP # try: request = urllib.request.Request(ip+path, body, headers) result = urllib.request.urlopen(request) #print(result.code) #print(result.info()) response = result.read().decode('utf-8') # except urllib.error.URLError: # response = 'Connection timed out.' return response def calibrationMenu(): print('CALIBRATION MENU\n\ \'1\'\tCalibration info\n\
\'2\'\tEmpty bed calibration\n\ \'3\'\tOccupied bed calibration\n\ \'esc\'\tExit calibration menu\n') while 1: keypress = msvcrt.getch() if keypress == chr(27).encode(): break elif keypress == str('1').encode(): # 4.12 Query BCG Calibration Status response = sendMessage('/bcg/cali',None) print(response) elif keypress == str('2').encode(): # 4.13 Start BCG Calibration (phase 1 = empty bed) response = sendMessage('/bcg/cali','{"phase": 1}'.encode('utf-8')) print(response)
if response == '{"errno": 0}': print('Starting empty bed calibration. (60s)')
print(str(0), end=" ", flush=True) # flush forces write
for i in range(1,7): time.sleep(10) print(str(i*10), end=" ", flush=True) print('\nEmpty bed calibration finished') else: print('Empty bed calibration start failed') print(response) # Read the HTTP API for response definitions
elif keypress == str('3').encode(): # 4.13 Start BCG Calibration (phase 2 = occupied bed) response = sendMessage('/bcg/cali','{"phase": 2}'.encode('utf-8')) print(response)
if response == '{"errno": 0}': print('Starting occupied bed calibration. (60s)') print(str(0), end=" ", flush=True) for i in range(1,7): Murata Electronics Oy SCA11H Doc.No. 3765

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Rev. 1



5 (5)

Rev.	Date	Change Description
1	09-June-17	First version.